

EAST Search History**EAST Search History (Prior Art)**

Ref #	Hits	Search Query	DBs	Default Operator	Plurals	Time Stamp
L1	5627	load with balanc\$4 and status and tracking	US_PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	OFF	2009/09/24 17:39
L2	565	load with balanc\$4 and status and tracking and (conveyor or robot\$4)	US_PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	OFF	2009/09/24 17:39
L3	213	load with balanc\$4 and status same (position\$4 or movement\$4) and tracking and (conveyor or robot\$4)	US_PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	OFF	2009/09/24 17:39
L4	201	load with balanc\$4 and status and tracking same (position\$4 or movement \$4) and (conveyor or robot \$4)	US_PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	OFF	2009/09/24 17:39
L5	28	load with balanc\$4 and status and tracking same (position\$4 or movement \$4) and (conveyor or robot \$4) and "700"/\$.ccls.	US_PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	OFF	2009/09/24 17:39
L6	39	load with balanc\$4 same (position\$4 or movement \$4) and (conveyor or robot \$4) and "700"/\$.ccls.	US_PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	OFF	2009/09/24 17:39
L7	52	load adj balanc\$4 and (position\$4 or movement \$4) same (conveyor or robot\$4) and "700"/\$.ccls.	US_PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	OFF	2009/09/24 17:39

L8	45	load adj balanc\$4 and (position\$4 or movement \$4) same (conveyor or robot\$4) and "700"/\$.ccls. not L6	US_PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	OFF	2009/09/24 17:39
L9	234	load adj balanc\$4 and (position\$4 or movement \$4) same (conveyor or robot\$4) and control\$4 with (data or message)	US_PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	OFF	2009/09/24 17:39
L10	726	robot\$4 with control with system and (stor\$4) and (status) with (data or signal or message or information) and control with signal	US_PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	OFF	2009/09/24 17:39
L11	354	robot\$4 with control with system and (stor\$4) and (status) with (data or signal or message or information or datum) and control with (data or signal or message or information) and "700"/\$.ccls.	US_PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	OFF	2009/09/24 17:39
L12	396	robot\$4 with control with system and (stor\$4) and (status) with (data or signal or message or information or datum) and control with (data or signal or message or information) and ("700"/\$.ccls. or "901"/\$.ccls.)	US_PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	OFF	2009/09/24 17:39
L13	51	robot\$4 with control with system.ab. and (stor\$4) and (status) with (data or signal or message or information or datum) and control with (data or signal or message or information) and ("700"/\$.ccls. or "901"/\$.ccls.)	US_PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	OFF	2009/09/24 17:39

L14	0	robot\$4 with control with system.ab. and (stor\$4) and (status) with (data or signal or message or information or datum) and control with (data or signal or message or information) and load adj balanc\$4	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	OFF	2009/09/24 17:39
L15	90	robot\$4 with control with system and (stor\$4) and (status) with (data or signal or message or information or datum) and control with (data or signal or message or information) and load adj balanc\$4	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	OFF	2009/09/24 17:39
L16	6	robot\$4 with control with system and (stor\$4) and (status) with (data or signal or message or information or datum) and control with (data or signal or message or information) and load adj balanc\$4 with (device or machine or equipment)	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	OFF	2009/09/24 17:39
L17	11	robot\$4 with control with system and (stor\$4) and (data or signal or message or information or datum) and control with (data or signal or message or information) and load adj balanc\$4 with (device or machine or equipment)	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	OFF	2009/09/24 17:39
L18	11	robot\$4 with control with system and (stor\$4) and control with (data or signal or message or information or datum) and load adj balanc\$4 with (device or machine or equipment)	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	OFF	2009/09/24 17:39

L19	4	robot\$4 with control with system and (stor\$4) and control with (data or signal or message or information or datum) and load adj balanc\$4 with (devices or machines or equipment)	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	OFF	2009/09/24 17:39
L20	5	(conveyor or robot\$4) same control with system and (stor\$4) and control with (data or signal or message or information or datum) and load adj balanc\$4 with (devices or machines or equipment)	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	OFF	2009/09/24 17:39
L21	4	(conveyor or robot\$4) same control with position \$4 and control with (data or signal or message or information or datum) and load adj balanc\$4 with (devices or machines or equipment)	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	OFF	2009/09/24 17:39
L22	15	(conveyor or robot\$4) same position\$4 and control with (data or signal or message or information or datum) and load adj balanc\$4 with (devices or machines or equipment)	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	OFF	2009/09/24 17:39
L23	24	(conveyor or robot\$4) same position\$4 and load adj balanc\$4 with (devices or machines or equipment)	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	OFF	2009/09/24 17:39
L24	130	(conveyor or robot\$4) and load adj balanc\$4 with (devices or machines or equipment)	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	OFF	2009/09/24 17:39
L25	72	load adj balanc\$4 same (equipment or devices or machines or components) and (conveyor or robot\$4) with control	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	OFF	2009/09/24 17:39

L26	290	load adj balanc\$4 and (equipment or devices or machines or components) and (conveyor or robot\$4) with control	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	OFF	2009/09/24 17:39
L27	190	load adj balanc\$4 with (equipment or devices or machines or components) and (conveyor or robot\$4)	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	OFF	2009/09/24 17:39
L28	130	load adj balanc\$4 with (equipment or devices or machines) and (conveyor or robot\$4)	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	OFF	2009/09/24 17:39
L29	276	load adj balanc\$4 and (semiconductor or wafer or rectile or lithograph) and position\$4 and (conveyor or robot\$4)	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	OFF	2009/09/24 17:39
L30	120	load adj balanc\$4 and (semiconductor or wafer or rectile or lithograph) and position\$4 same (conveyor or robot\$4)	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	OFF	2009/09/24 17:39
L31	120	load adj balanc\$4 and (semiconductor or wafer or rectile or lithograph) and position\$4 same (conveyor or robot\$4)	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	OFF	2009/09/24 17:39
L32	14	line adj balanc\$4 and (semiconductor or wafer or rectile or lithograph) and position\$4 same (conveyor or robot\$4)	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	OFF	2009/09/24 17:39
L33	134	line adj balancing and position\$4 with control	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	OFF	2009/09/24 17:39

L34	4	line adj balancing and position\$4 with control and (robots or robotic)	US_PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	OFF	2009/09/24 17:39
L35	0	line adj balancing and position\$4 with (robots or robotic)	US_PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	OFF	2009/09/24 17:39
L36	1	line adj balancing and position\$4 with (robot or robotic)	US_PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	OFF	2009/09/24 17:39
L37	10	line adj balanc\$4 and position\$4 with (robot or robotic)	US_PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	OFF	2009/09/24 17:39
L38	17	line adj balanc\$4 and position\$4 same (robot or robotic)	US_PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	OFF	2009/09/24 17:39
L39	12	(repeat\$4 or continous) with triggering and position\$4 same (robot or robotic)	US_PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	OFF	2009/09/24 17:39
L40	18	(repeat\$4 or continuous) with triggering and position\$4 same (robot or robotic)	US_PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	OFF	2009/09/24 17:39
L41	80	(repeat\$4 or continuous) with (sending or triggering) with (signal or message or data or information or command) and position\$4 and (robot or robotic)	US_PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	OFF	2009/09/24 17:39

L42	7	(repeat\$4 or continuous) with (sending or triggering) with (signal or message or data or information or command) and position\$4 and (robot or robotic) and balancing	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	OFF	2009/09/24 17:39
L43	80	(repeat\$4 or continuous) with (sending or triggering) with (signal or message or data or information or command) and position\$4 and (robot or robotic)	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	OFF	2009/09/24 17:39
L44	16	line adj2 balancing and robot\$4	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	OFF	2009/09/24 17:39
L45	0	command with signal with all with (devices or machines or equipment)	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	OFF	2009/09/24 17:39
L46	0	command with all with (devices or machines or equipment)	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	OFF	2009/09/24 17:39
L47	0	signal with all with (devices or machines or equipment)	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	OFF	2009/09/24 17:39
L48	4	positioning with (every or all) with (devices or machines or equipment) same robot\$4	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	OFF	2009/09/24 17:39
L49	4	positioning with (every or ""all"") with (devices or machines or equipment) same robot\$4	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	OFF	2009/09/24 17:39

L50	4	positioning same (every or ""all"") with (devices or machines or equipment) same robot\$4	US_PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	OFF	2009/09/24 17:39
L51	63	(information or datum or command or data) same (every or ""all"") with (devices or machines or equipment) same robot\$4	US_PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	OFF	2009/09/24 17:39
L52	26	(information or datum or command or data) same broadcast same (devices or machines or equipment) same robot\$4	US_PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	OFF	2009/09/24 17:39
L53	396	conveyor and broadcast with (signal or output or input or command)	US_PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	OFF	2009/09/24 17:39
L54	533	conveyor and broadcast with (signal or output or input or command or data or datum)	US_PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	OFF	2009/09/24 17:39
L55	54	conveyor and broadcast with (signal or output or input or command or data or datum) with (move\$4 or position\$4 or placement or place\$5)	US_PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	OFF	2009/09/24 17:39
L56	67	(robot\$4 or conveyor) and broadcast with (signal or output or input or command or data or datum) with (move\$4 or position\$4 or placement or place\$5) same (devices or equipment or machines or components or elements)	US_PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	OFF	2009/09/24 17:39

L57	35	(assembly near2 (line or system)) and broadcast with (signal or output or input or command or data or datum) with (move\$4 or position\$4 or placement or place\$5) same (devices or equipment or machines or components or elements)	US_PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	OFF	2009/09/24 17:39
L58	120	scheduling and broadcast with (signal or output or input or command or data or datum) with (move\$4 or position\$4 or placement or place\$5) same (devices or equipment or machines or components or elements)	US_PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	OFF	2009/09/24 17:39
L59	96	scheduling and broadcast with (signal or output or input or command or data or datum) with (move\$4 or position\$4 or placement or place\$5) same (devices or equipment or machines)	US_PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	OFF	2009/09/24 17:39
L60	357	electronic adj cam	US_PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	OFF	2009/09/24 17:39
L61	0	electronic adj cam and load adj balancing	US_PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	OFF	2009/09/24 17:39
L62	534	broadcast with control with (machines or equipment or cam or devices) and index\$3	US_PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	OFF	2009/09/24 17:39
L63	38	electronic adj cam and index\$4	US_PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	OFF	2009/09/24 17:39

L64	196	broadcast with control with (machines or equipment or cam or devices and pick near2 pul) and index\$3	US_PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	OFF	2009/09/24 17:39
L65	196	broadcast with control with (machines or equipment or cam or devices and pick near2 pull) and index\$3	US_PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	OFF	2009/09/24 17:39
L66	0	broadcast with control with (pick near2 pull) and index\$3	US_PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	OFF	2009/09/24 17:39
L67	0	broadcast with control with (pick near2 pull)	US_PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	OFF	2009/09/24 17:39
L68	0	broadcast with control with (pick with pull)	US_PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	OFF	2009/09/24 17:39
L69	0	broadcast with control same (pull near2 pull)	US_PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	OFF	2009/09/24 17:39
L70	60	control same (pull near2 pull) and broadcast	US_PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	OFF	2009/09/24 17:39
L71	318	broadcast and robot\$4 with assembl\$4	US_PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	OFF	2009/09/24 17:39

L72	187	broadcast and robot\$4 with assembl\$4 and central	US_PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	OFF	2009/09/24 17:39
L73	367	(700/247).CCLS.	US_PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	OFF	2009/09/24 17:39
L74	335	L73 and (plurality or robots)	US_PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	OFF	2009/09/24 17:39
L75	56	L73 and (plurality with robots)	US_PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	OFF	2009/09/24 17:39
L76	108	(synchron\$6 or coordinat\$4 or cooperat\$5) same (numerous or plurality or several) near2 robots and (central or primary or master) with (controller or processor or control or cpu or computer or device or component)	US_PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	OFF	2009/09/24 17:39
L77	80	(synchron\$6 or coordinat\$4 or cooperat\$5) same (numerous or plurality or several) near2 robots and (central or primary or master) with (controller or processor or control or cpu or computer or device or component) and ("700"/\$.ccls. or "901"/\$.ccls.)	US_PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	OFF	2009/09/24 17:39

L78	21	(synchron\$6 or coordinat\$4 or cooperat\$5) same (numerous or plurality or several) near2 robots and (central or primary or master) with (controller or processor or control or cpu or computer or device or component) and ("700"/\$.ccls. or "901"/\$.ccls.) and (buffer\$4 or index\$4)	US_PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	OFF	2009/09/24 17:39
L79	8	(synchron\$6 or coordinat\$4 or cooperat\$5) same (numerous or plurality or several) near2 robots and (central or primary or master) with (controller or processor or control or cpu or computer or device or component) and adaptive with control\$4	US_PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	OFF	2009/09/24 17:39
L80	48	(synchron\$6 or coordinat\$4 or cooperat\$5) same (numerous or plurality or several) with robots and (central or primary or master) with (controller or processor or control or cpu or computer or device or component) and sort\$\$	US_PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	OFF	2009/09/24 17:39
L81	48	(synchron\$6 or coordinat\$4 or cooperat\$5) same (numerous or plurality or several) with robots and (central or primary or master) with (controller or processor or control or cpu or computer or device or component) and sort\$4	US_PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	OFF	2009/09/24 17:39
L82	27	(synchron\$6 or coordinat\$4 or cooperat\$5) same (numerous or plurality or several) near4 robots and (central or primary or master) with (controller or processor or control or cpu or computer or device or component) and (sort\$4 or pick with pull)	US_PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	OFF	2009/09/24 17:39

L83	0	(synchron\$6 or coordinat\$4 or cooperat\$5) same (numerous or plurality or several) near4 robots and (central or primary or master) with (controller or processor or control or cpu or computer or device or component) and (pick with pull)	US_PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	OFF	2009/09/24 17:39
L84	0	(synchron\$6 or coordinat\$4 or cooperat\$5) same (numerous or plurality or several) with robots and (central or primary or master) with (controller or processor or control or cpu or computer or device or component) and (pick with pull)	US_PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	OFF	2009/09/24 17:39
L85	0	(synchron\$6 or coordinat\$4 or cooperat\$5) same (numerous or plurality or several) with robots and (central or primary or master) with (controller or processor or control or cpu or computer or device or component) and (pick near3 pull)	US_PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	OFF	2009/09/24 17:39
L86	0	(synchron\$6 or coordinat\$4 or cooperat\$5) same (numerous or plurality or several) same robots and (central or primary or master) with (controller or processor or control or cpu or computer or device or component) and (pick near3 pull)	US_PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	OFF	2009/09/24 17:39
L87	0	(synchron\$6 or coordinat\$4 or cooperat\$5) same (numerous or plurality or several) and robots and (central or primary or master) with (controller or processor or control or cpu or computer or device or component) and (pick near3 pull)	US_PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	OFF	2009/09/24 17:39

L88	596	(pick near3 pull)	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	OFF	2009/09/24 17:39
L89	352	(700/250).CCLS.	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	OFF	2009/09/24 17:39
L90	715	(700/259).CCLS.	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	OFF	2009/09/24 17:39
L91	1380	(L1 L2 L3 L4 L5 L6 L7 L8 L9 L10 L11 L12 L13 L14 L15 L16 L17 L18 L19 L20 L21 L22 L23 L24 L25 L26 L27 L28 L29 L30 L31 L32 L33 L34 L35 L36 L37 L38 L39 L40 L41 L42 L43 L44 L45 L46 L47 L48 L49 L50 L51 L52 L53 L54 L55 L56 L57 L58 L59 L60 L61 L62 L63 L64 L65 L66 L67 L68 L69 L70 L71 L72 L73 L74 L75 L76 L77 L78 L79 L80 L81 L82 L83 L84 L85 L86 L87 L88 L89 L90) and @pd>"20081027"	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2009/09/24 17:39

9/24/2009 5:57:29 PM

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